

# Mrunal Sarvaiya

📍 Brooklyn, New York, US    ✉ mrunal.s@nyu.edu    🔗 mrunaljsarvaiya.github.io

## Education

---

- New York University** Brooklyn, NY  
*PhD Candidate in Electrical and Computer Engineering* Aug 2023 – present  
◦ [Agile Robotics and Perception Lab](#) 🔗
- University of California, Berkeley** Berkeley, CA  
*M.Eng in Control of Robotic and Autonomous Systems* Aug 2018 – May 2019  
◦ GPA: 3.70/4.0
- Stanford Center For Professional Development** Jan 2022 – May 2023  
*Graduate Coursework in AI Graduate Program*  
◦ GPA: 3.77/4.30
- University Of Illinois At Urbana-Champaign** Champaign, IL  
*B.S. in Mechanical Engineering with Highest Honors* Aug 2014 – May 2018  
◦ GPA: 3.89/4.0

## Publications

---

- HPA-MPC: Hybrid Perception-Aware Nonlinear Model Predictive Control for Quadrotors with Suspended Loads** Nov 2024  
Mrunal Sarvaiya, Guanrui Li, Giuseppe Loianno  
[mrunaljsarvaiya.github.io/hpa-mpc.github.io](https://mrunaljsarvaiya.github.io/hpa-mpc.github.io) 🔗

## Experience

---

- Senior Robotics Software Engineer** San Francisco, CA  
*Peanut Robotics* Aug 2019 – Aug 2023  
◦ Developed the motion planning software architecture for a custom mobile manipulator  
◦ Selected, integrated and tuned a trajectory tracking controller and time optimal trajectory generator (TOPPRA)  
◦ Designed and implemented a custom navigation planner for hotel hallways that generates human-like and aesthetically pleasing motions  
◦ Trained a neural network model to estimate manipulator currents. The model was used to add trajectory generator torque constraints for enhanced reliability  
◦ Engineered tools to optimize robot paths by smoothing trajectories and reducing, overall joint-space distance by tweaking input configurations using an optimization program
- Controls and Software Engineer (M.Eng. Capstone)** Berkeley, CA  
*Squishy Robotics* Aug 2018 – May 2019  
◦ Implemented and tuned a path planning technique using A-star and MPC for a Tensegrity robot  
◦ Increased range of communication by 200% by integrating long range radio software  
◦ Developed software that allowed interchangeable use of different frequency radios
- R&D Test Systems Engineering Intern** Palo Alto, CA  
*Tesla, Inc* May 2018 – Aug 2018  
◦ Created a Python program that automated data logging and was deployed on over 20 workstations replacing hardware worth over \$5,000 per dynamometer workstation  
◦ Increased data accessibility and reduced post processing time by uploading data to a company-wide server which is accessed by a Jenkins pipeline  
◦ Reduced complexity of non-standard test scripts by integrating python into the existing testing architecture
- Team President and Business Team Lead Presenter** Champaign, IL  
*Illini Motorsports (Formula SAE)* Aug 2015 – May 2018  
◦ Managed and allocated a \$30,000+ budget for 6 subsystems for a team of 80 students

- Raised funds by building relationships with 10 corporate sponsors and represented the team at major university outreach events
- Secured four top 3 finishes as the business team presenter at international university competitions
- Optimized vehicle intake geometry using GT-Power simulations, increasing engine power output by 2 HP
- Led a team of 6 students to design and validate a new vehicle radiator and fan

### **Research Assistant**

*Advanced Controls Research Laboratory (Dr. Naira Hovakimyan)*

*Champaign, IL  
May 2017 – Mar 2018*

- Developed a genetic algorithm in Matlab to find the best path for multiple drones given time, velocity, acceleration and space constraints
- Programmed an on-board controller for the motor that increased precision of the manipulator arm by 40% and increased range of motion by 100%
- Reduced complexity of non-standard test scripts by integrating python into the existing testing architecture

### **Awards**

---

#### **Top 3 in the Business and Sales Presentation event**

*Formula SAE at UIUC*

*Champaign, IL  
May 2018*

- FSAE Michigan 2016, 2017, 2018 and FSAE Lincoln 2016, 2017, 2018

#### **GM/Philip W. Leistra Jr. Society of Automotive Engineers Award**

*Mechanical Engineering Dept at UIUC*

*Champaign, IL  
Mar 2018*

- Recognized for contributions to the Formula SAE team

#### **Dean's List**

*Mechanical Engineering Dept at UIUC*

*Champaign, IL  
May 2018*

- Awarded every semester except Spring 2018